

Zero stability for the one-row colored  
 $sl_3$  Jones polynomial

Main result.

$\{ J_{K, (n,0)}^{sl_3}(q) \}$  for "minus-adequate link"  $K$ .

then,  $\exists J_K^{sl_3}(q) \in \mathbb{Z}[[q]]$

s.t.  $\lim_{n \rightarrow \infty} J_{K, (n,0)}^{sl_3}(q) = J_K^{sl_3}(q)$

Friday Seminar on Knot Theory

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## ① Colored Jones polynomial

$\{J_{K,n}^{\mathfrak{sl}_2}(\mathfrak{q})\}_n \in \mathbb{Q}(\mathfrak{q})$  or  $\mathbb{C}$  or ...  
 (n+1)-dim. irr. of  $\mathfrak{sl}_2$   
 knots & link.  
 ( a family of invariants of knots & Links )

$J_{K,1}^{\mathfrak{sl}_2}(\mathfrak{q})$  : the Jones polynomial  
 $J_{\text{unknot},1}^{\mathfrak{sl}_2}(\mathfrak{q}) = -[2]$   
 $= -\mathfrak{q}^{\frac{1}{2}} - \mathfrak{q}^{-\frac{1}{2}}$   
 $[n] := \frac{\mathfrak{q}^{\frac{n}{2}} - \mathfrak{q}^{-\frac{n}{2}}}{\mathfrak{q}^{\frac{1}{2}} - \mathfrak{q}^{-\frac{1}{2}}}$

} for simple Lie alg.  $\mathfrak{g}$

$+ V_\lambda$  : irr.  
 $\uparrow$   
 h.w.

## ② Colored $\mathfrak{g}$ Jones polynomial

$\{J_{K,\lambda}^{\mathfrak{g}}(\mathfrak{q})\}_\lambda$      $\mathfrak{g} = \mathfrak{sl}_3$   
 $\lambda \in \{(n,m) \in \mathbb{Z}_{\geq 0} \times \mathbb{Z}_{\geq 0}\}$

one-row :  $\{(n,0) \mid n \in \mathbb{Z}\}$   
 colors

## ① Properties of the CJP

**Theorem [Lê, 2000]**

$J_{L,\lambda}^{\mathfrak{g}}(\mathfrak{q}) \in \mathfrak{q}^{\frac{P}{2}} \mathbb{Z}[\mathfrak{q}^{\pm 1}]$   
 (Integrality)  
 determined by  $\mathfrak{g}$

(Integrality)

Define  $\delta_K^*(\lambda) := \text{mindeg}(J_{K,\lambda}^{\mathfrak{g}}(\mathfrak{q}))$   
 minimum deg.

} normalization

$$\begin{aligned}
 \hat{J}_{K,\lambda}^{\mathfrak{g}}(\mathfrak{q}) &:= \pm \mathfrak{q}^{-\delta_K^*(\lambda)} J_{K,\lambda}^{\mathfrak{g}}(\mathfrak{q}) \in \mathbb{Z}[\mathfrak{q}] \\
 &= \sum_{i=0} a_i \mathfrak{q}^i \quad (a_0 > 0)
 \end{aligned}$$



# ① Stability

## Theorem [Dasbach-Lin, 06]

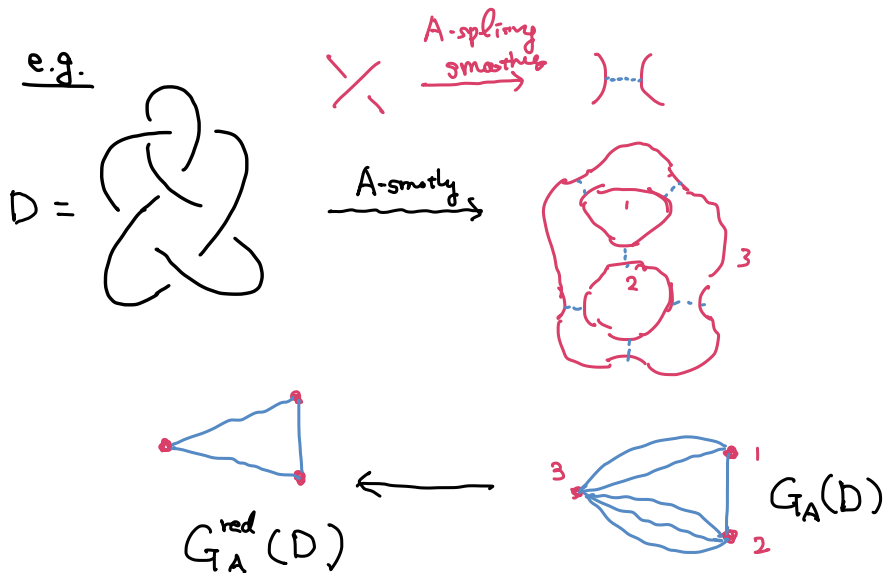
- $K$ : an  $A$ -adequate knot
- $D$ : an  $A$ -adequate knot diagram
- $G^{\text{red}}(D)$ : a reduced  $A$ -graph of  $D$

$$J_{K,n}^{\text{rel}_2'}(\varrho) = a_n A^{kn} + b_n A^{kn-4} + \dots + \beta_n A^{ln+4} + \alpha_n A^{ln}$$

$(\varrho = A^4)$ 
↑ the highest degree
the lowest degree
↑

some normalization

then,  $a_n$  and  $b_n$  are determined by  $G^{\text{red}}(D)$ .



- Volume-ish theorem for CJP.
- $K$ : an alternating prime, non-torus knot.
- then,

$$2v_0 \cdot (\max(|b_n|, |\beta_n|) - 1) \leq \text{Vol}(S^3 - K) \leq 10v_0 \cdot (|b_n| + |\beta_n| - 1)$$

for all  $n$ .

$v_0$  = the volume of an ideal regular hyperbolic tetrahedron.

### Theorem[Armond, 2013]

$K$ : an  $A$ -adequate link.

then,  $\exists \mathcal{J}_K^{sl_2}(\mathcal{L}) \in \mathbb{Z}[[\mathcal{L}]]$  s.t

$$\hat{\mathcal{J}}_{K,n}^{sl_2}(\mathcal{L}) - \mathcal{J}_K^{sl_2}(\mathcal{L}) \in \mathcal{L}^{n+1} \mathbb{Z}[[\mathcal{L}]]$$

↑ tail of  $\{\hat{\mathcal{J}}_{K,n}^{sl_2}(\mathcal{L})\}$

### Theorem[Armond-Dasbach, 2016]

$K$ : an  $A$ -adequate link.

$D$ : an  $A$ -adequate knot diagram of  $K$ .

then  $\mathcal{J}_K^{sl_2}(\mathcal{L})$  only depends on  $G^{\text{red}}(D)$

### Theorem[Garoufalidis-Lê, 2015]

$K$ : an alternating link.

then  $\{\hat{\mathcal{J}}_{K,n}^{sl_2}(\mathcal{L})\}$  is  $k$ -stable ( $\forall k \geq 0$ )

•  $\{f_n(\mathcal{L}) \in \mathbb{Z}[[\mathcal{L}]]\}_n$  is  $k$ -stable

if  $\exists \Phi_0(\mathcal{L}), \dots, \exists \Phi_k(\mathcal{L}) \in \mathbb{Z}((\mathcal{L}))$

$$\text{s.t. } \lim_{n \rightarrow \infty} \mathcal{L}^{k(n+1)} \left( f_n(\mathcal{L}) - \sum_{j=0}^k \Phi_j(\mathcal{L}) \mathcal{L}^{j(n+1)} \right) = 0$$

$$\left( \begin{array}{l} \text{⊗} \cdot \lim_{n \rightarrow \infty} f_n(\mathcal{L}) = \Phi(\mathcal{L}) \\ \iff \forall m \in \mathbb{N}, \exists N_m \in \mathbb{N} \\ \text{def} \\ \text{s.t. } f_{N_m}(\mathcal{L}) - \Phi(\mathcal{L}) \in \mathcal{L}^m \mathbb{Z}[[\mathcal{L}]] \end{array} \right)$$

e.g.  $N_m = m-1$  if  $f_n(z) = \hat{J}_{K,n}^{alt}(z)$ ,  $K$ : alternating  
 $= \sum_{j=0}^{\infty} a_j(n) z^j$

$\sum_{j=0}^{\infty} a_j z^j$

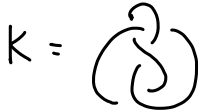
0-stable:  $\lim_{n \rightarrow \infty} (f_n(z) - \Phi_0(z)) = 0$

$\Leftrightarrow \underbrace{f_n(z) - \Phi_0(z)}_{\text{tail}} \in z^{n+1} \mathbb{Z}[[z]]$

$\frac{(a_{n+1}(n) - a_{n+1}) z^{n+1} + (a_{n+2}(n) - a_{n+2}) z^{n+2} + \dots}{b_0(n)}$

1-stable:  $\lim_{n \rightarrow \infty} (z^{-n+1} (f_n(z) - \Phi_0(z)) - \Phi_1(z)) = 0$

$\sum_{j=0}^{\infty} b_j z^j$



$z^0 z^1 z^2 z^3 \dots$

|          |   |    |    |   |   |   |    |    |    |    |    |    |    |    |    |    |     |
|----------|---|----|----|---|---|---|----|----|----|----|----|----|----|----|----|----|-----|
| $\Phi_0$ | 1 | -1 | -1 | 0 | 0 | 1 | 0  | 1  | 0  | 0  | 0  | 0  | -1 | 0  | 0  | -1 | ... |
| $N=2$    | 1 | -1 | -1 | 0 | 2 | 0 | -2 | 0  | 3  | 0  | -3 | 0  | 3  | 0  | -3 | 0  | ... |
| $N=3$    | 1 | -1 | -1 | 0 | 0 | 3 | -1 | -1 | -1 | -1 | 5  | -1 | -2 | -2 | -1 | 6  | ... |
| $N=4$    | 1 | -1 | -1 | 0 | 0 | 1 | 2  | 0  | -2 | -1 | -1 | 1  | 3  | 1  | -2 | -3 | ... |

|          |   |    |    |    |    |    |   |    |    |     |    |     |    |   |   |    |     |
|----------|---|----|----|----|----|----|---|----|----|-----|----|-----|----|---|---|----|-----|
| $\Phi_0$ | 1 | -1 | -1 | 0  | 0  | 1  | 0 | 1  | 0  | 0   | 0  | 0   | -1 | 0 | 0 | -1 | ... |
| $N=2$    | 0 | 2  | -1 | -2 | -1 | 3  | 0 | -3 | 0  | 4   | 0  | ... |    |   |   |    |     |
| $N=3$    | 0 | 2  | -1 | -2 | -1 | -1 | 5 | -1 | -1 | -2  | -1 | ... |    |   |   |    |     |
| $N=4$    | 0 | 2  | -1 | -2 | -1 | -1 | 4 | 1  | -2 | ... |    |     |    |   |   |    |     |

$\Phi_1$  0 2 -1 -2 -1 -1 1 ...



$\Phi_2$



$\Phi_3$



$\Phi_k$

**Theorem[Garoufalidis-Vuong, 2017]**

$K$ : a trus knot

$\mathfrak{g} = \mathfrak{sl}_3$

$\mathfrak{g}$ : a rank 2 simple Lie algebra.

then,  $\{J_{K, n, \lambda}^{\mathfrak{g}}(\mathfrak{q})\}_n$  is  $c$ -stable  $\leftarrow$  stable + "cyclotomic"  
 $\uparrow$  cyclotomically

**Theorem[Y.]**

$K$ : a "minus-adequate" oriented link.

$\exists J_K^{\mathfrak{sl}_3}(\mathfrak{q}) \in \mathbb{Z}[[\mathfrak{q}]]$  s.t.

$J_{K, (n, 0)}^{\mathfrak{sl}_3}(\mathfrak{q}) - J_K^{\mathfrak{sl}_3}(\mathfrak{q}) \in \mathfrak{q}^{n+1} \mathbb{Z}[[\mathfrak{q}]]$

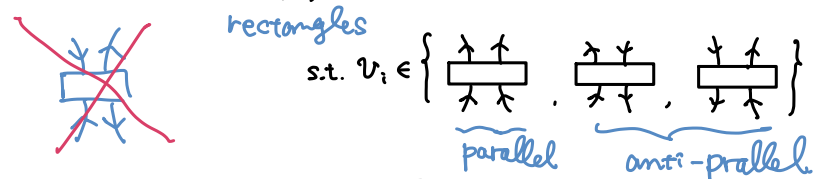
i.e.  $\{J_{K, (n, 0)}^{\mathfrak{sl}_3}(\mathfrak{q})\}$  is zero stable

"minus-adequate" oriented link.

Consider an embeded 4-valent graph into  $\mathbb{R}^2$

$G(v_1, v_2, \dots, v_\ell)$

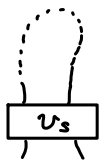
with  $\left\{ \begin{array}{l} \text{oriented edges} \\ \text{vertices} = \{v_1, v_2, \dots, v_\ell\} \\ \text{(boxes)} \end{array} \right.$



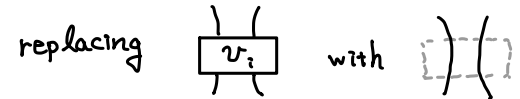
then  $G(v_1, v_2, \dots, v_\ell)$  is adequate

if  $\forall s \in \{1, 2, \dots, \ell\}$ , there is no arcs

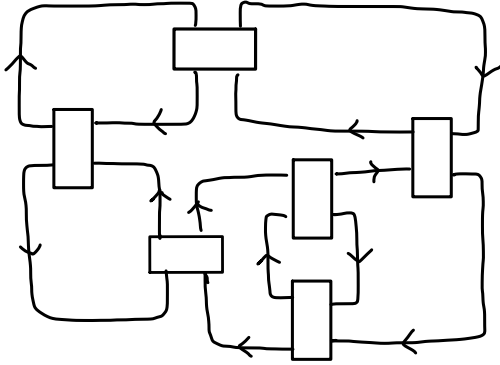
in  $G(\bar{v}_1, \dots, \bar{v}_{s-1}, v_s, \bar{v}_{s+1}, \dots, \bar{v}_\ell)$  s.t.



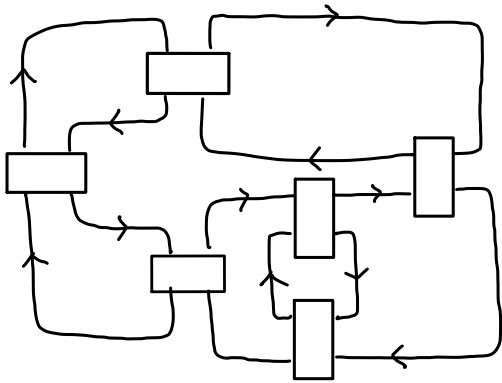
where  $\bar{v}_i$  means



e.g.



adequate

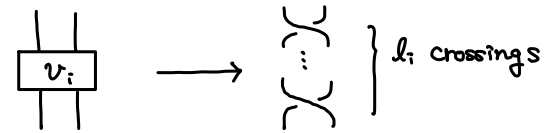


inadequate

• an oriented link diagram  $D$  is minus-adequate

if  $\exists$  an adequate graph  $G(v_1, \dots, v_x)$

s.t.  $D$  is obtained by replacing



( $\times$  anti-parallel  $\Rightarrow l_i : \text{even}$ )



e.g.

