

The tail of the one-row colored $sl(3)$ Jones polynomial
and the Andrews - Gordon type identity

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§1 Quick Introduction to Quantum Invariants
of Knots and Links

① Diagrammatic definition of knots & links

an l -component link diagram D

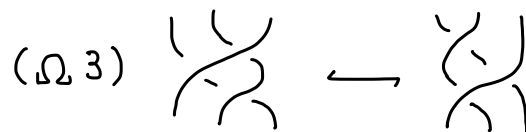
$\Leftrightarrow D: \coprod S^1 \longrightarrow \mathbb{R}^2$, an generic immersion

with over/under information
on intersection points.

i.e. intersection points



Reidemeister moves



the set of l -component links

$\equiv \{ l\text{-component link diagrams} \} /$
 $(R1)$
 $(R2)$
 $(R3)$
 $+ \text{isotopy}$

i.e. $[D] = [D']$

D and D' are related by
a finite sequence of $(R1)$, $(R2)$, $(R3)$
 $+ \text{isotopy}$

Oriented links

- link diagram + orientation on the image of S'
- equivalence : orientation preserving (Ω_1) (Ω_2) (Ω_3) moves

framed links

- equivalence : (Ω_0) (Ω_2) (Ω_3) moves

$$(\Omega_0) \begin{array}{c} | \\ \circlearrowleft \\ | \end{array} \longleftrightarrow |$$

⑦ Quantum invariants

of knots and links

a (k, l) -tangle diagram

$\stackrel{\text{def}}{\iff}$ a generic immersion of arcs & loops into $\mathbb{R} \times [0, 1]$

- s.t. • intersection point = \times
- $\partial\{\text{arcs}\} = \{(1,0), (2,0), \dots, (k,0)\} \cup \{(1,1), (2,1), \dots, (l,1)\}$



$(5, 3)$ -tangle diagram

the set of framed (k, l) -tangles

$$:= \left\{ (k, l)\text{-tangle diagram} \right\} / \begin{matrix} (\Omega 0), (\Omega 2), \\ (\Omega 3), \text{isotopy} \end{matrix}$$

Fix a strict ribbon category \mathcal{C}

$$\left[\begin{array}{l} \text{braiding } C_{V,W} : V \otimes W \rightarrow W \otimes V \\ \text{duality } \left\{ \begin{array}{l} * : V \rightarrow V^* \\ b_V : \mathbb{1} \rightarrow V \otimes V^* \\ d_V : V^* \otimes V \rightarrow \mathbb{1} \end{array} \right. \\ \text{twist } \theta_V : V \rightarrow V, \text{ isom.} \end{array} \right]$$

a category of \mathcal{C} -colored framed tangles $\mathcal{T}_{\mathcal{C}}$

$\stackrel{\text{def}}{\iff}$ $\text{Obj } \mathcal{T}_{\mathcal{C}}$: a finite sequence of $\text{Obj } \mathcal{C} \times \{+, -\}$
 $\hookrightarrow \emptyset$: the empty sequence.

$$\text{Obj } \mathcal{T}_{\mathcal{C}} \ni \eta_1 = ((V_1, \varepsilon_1), (V_2, \varepsilon_2), \dots, (V_k, \varepsilon_k))$$

$$\eta_2 = ((W_1, \delta_1), (W_2, \delta_2), \dots, (W_l, \delta_l))$$

$\text{Mor}(\eta_1, \eta_2)$: an oriented framed (k, l) -tangle

s.t. • each component is colored by $\text{Obj } \mathcal{C}$

$$\bullet \frac{\overset{(i,1)}{\downarrow}}{V_i} \text{ if } \varepsilon_i = +, \quad \frac{\overset{(i,1)}{\uparrow}}{V_i} \text{ if } \varepsilon_i = -$$

$$\frac{\downarrow}{W_i} \text{ if } \delta_i = +, \quad \frac{\uparrow}{W_i} \text{ if } \delta_i = -$$

Fix a strict ribbon category \mathcal{C}

$$\left[\begin{array}{l} \text{braiding } C_{V,W}: V \otimes W \rightarrow W \otimes V \\ \text{duality } \left\{ \begin{array}{l} * : V \rightarrow V^* \\ b_V: \mathbb{1} \rightarrow V \otimes V^* \\ d_V: V^* \otimes V \rightarrow \mathbb{1} \end{array} \right. \\ \text{twist } \theta_V: V \rightarrow V, \text{ isom.} \end{array} \right]$$

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$$\eta_2 = ((W_1, \delta_1), (W_2, \delta_2), \dots, (W_\ell, \delta_\ell))$$

- $\text{Mor}(\eta_1, \eta_2)$: an oriented framed (k, ℓ) -tangle

s.t. • each component is colored by $\text{Obj } \mathcal{C}$

$$\bullet \begin{array}{l} \begin{array}{c} (i,1) \\ \downarrow \\ V_i \end{array} \text{ if } \varepsilon_i = +, \quad \begin{array}{c} (i,1) \\ \uparrow \\ V_i \end{array} \text{ if } \varepsilon_i = - \\ \\ \begin{array}{c} \downarrow \\ W_i \end{array} \text{ if } \delta_i = +, \quad \begin{array}{c} \uparrow \\ W_i \end{array} \text{ if } \delta_i = - \end{array}$$

- composition

$$\boxed{T_1} \circ \boxed{T_2} := \boxed{\begin{array}{c} T_1 \\ \hline T_2 \end{array}}$$

- tensor product

$$\boxed{T_1} \otimes \boxed{T_2} := \boxed{\begin{array}{c|c} T_1 & T_2 \end{array}}$$

Theorem [Reshetikhin-Turaev, 1990]

$\exists! F_{\mathcal{C}}: \mathcal{T}_{\mathcal{C}} \rightarrow \mathcal{C}$, a \otimes -preserving functor

s.t. $F((V, +)) = V$, $F((V, -)) = V^*$

$$\begin{array}{c} W \\ \swarrow \searrow \\ V \end{array} = C_{V,W} \quad \begin{array}{c} W \\ \swarrow \nwarrow \\ V \end{array} = C_{W,V}^{-1} \quad \begin{array}{c} W \\ \swarrow \nearrow \\ V \end{array} = C_{W,V^*}^{-1} \quad \begin{array}{c} W \\ \swarrow \nwarrow \\ V \end{array} = C_{V^*,W}$$

$$\begin{array}{c} W \\ \nwarrow \swarrow \\ V \end{array} = C_{W^*,V}^{-1} \quad \begin{array}{c} W \\ \nwarrow \nwarrow \\ V \end{array} = C_{V,W^*} \quad \begin{array}{c} W \\ \nwarrow \nearrow \\ V \end{array} = C_{V,W^*} \quad \begin{array}{c} W \\ \nwarrow \swarrow \\ V \end{array} = C_{W^*,V^*}^{-1}$$

$$V \downarrow = \text{id}_V \quad V \uparrow = \text{id}_{V^*} \quad V \downarrow \circ = \theta_V \quad V \uparrow \circ = \theta_V^{-1}$$

$$V \downarrow \circ = d_V \quad V \uparrow \circ = b_V \quad \left(\begin{array}{c} V \\ \downarrow \circ \end{array} = \begin{array}{c} \circ \\ \downarrow \end{array} \quad \begin{array}{c} \uparrow \circ \\ V \end{array} = \begin{array}{c} \uparrow \\ \circ \end{array} \right)$$

Theorem [Reshetikhin-Turaev, 1990]

$\exists! F_e: \mathcal{T}_e \rightarrow \mathcal{C}$, a \otimes -preserving functor

s.t. $F((v, +)) = V$, $F((v, -)) = V^*$

$$\begin{array}{c} w \\ \swarrow \searrow \\ \downarrow \\ \swarrow \searrow \\ v \end{array} = c_{v,w} \quad \begin{array}{c} w \\ \swarrow \searrow \\ \downarrow \\ \swarrow \searrow \\ v \end{array} = c_{w,v}^{-1} \quad \begin{array}{c} w \\ \swarrow \searrow \\ \downarrow \\ \swarrow \searrow \\ v \end{array} = c_{w,v^*}^{-1} \quad \begin{array}{c} w \\ \swarrow \searrow \\ \downarrow \\ \swarrow \searrow \\ v \end{array} = c_{v^*,w}$$

$$\begin{array}{c} w \\ \swarrow \searrow \\ \downarrow \\ \swarrow \searrow \\ v \end{array} = c_{w^*,v}^{-1} \quad \begin{array}{c} w \\ \swarrow \searrow \\ \downarrow \\ \swarrow \searrow \\ v \end{array} = c_{v,w^*} \quad \begin{array}{c} w \\ \swarrow \searrow \\ \downarrow \\ \swarrow \searrow \\ v \end{array} = c_{v,w^*} \quad \begin{array}{c} w \\ \swarrow \searrow \\ \downarrow \\ \swarrow \searrow \\ v \end{array} = c_{w^*,v^*}^{-1}$$

$$v \downarrow = \text{id}_V \quad v \uparrow = \text{id}_{V^*} \quad v \uparrow \downarrow = \theta_V \quad v \downarrow \uparrow = \theta_V^{-1}$$

$$\begin{array}{c} v \\ \downarrow \\ \downarrow \end{array} = d_V \quad \begin{array}{c} v \\ \downarrow \\ \downarrow \end{array} = b_V$$

$\rightsquigarrow L$: an \mathcal{C} -colored framed link.

$$\Rightarrow F_e(L) \in \text{End}(\mathbb{1})$$

e.g. (the quantum \mathfrak{g} invariant of framed links, the colored \mathfrak{g} Jones polynomial)

\mathfrak{g} : a simple Lie algebra

$\text{Rep}_f U_q(\mathfrak{g})$: the category of finite dimensional representations of the quantum group $U_q(\mathfrak{g})$. ($q = "q^2"$: a formal variable)

$L = L_1 \sqcup L_2 \sqcup \dots \sqcup L_n$: a framed link

$V_i \in \text{Rep}_f U_q(\mathfrak{g})$ is a coloring of L_i

the $(\mathfrak{g}, (V_1, \dots, V_n))$ -colored Jones polynomial

$J_L^{\mathfrak{g}}(V_1, V_2, \dots, V_n) \in \mathbb{C}(q^{\pm 1})$ is defined by

$$F_e(L)(1) = J_L^{\mathfrak{g}}(V_1, V_2, \dots, V_n) \cdot 1$$

(\ast : D is determined by \mathfrak{g})



§ 2 Stability of the Colored Jones Polynomial

⊙ Properties of the CJP

Theorem [Lê, 2000] (Integrality)

$$J_L^{\mathfrak{g}}(V_{\lambda_1}, V_{\lambda_2}, \dots, V_{\lambda_r}) \in \mathfrak{q}^{\frac{P}{2}} \mathbb{Z}[\mathfrak{q}^{\pm 1}]$$

Theorem [Garoufalidis-Lê, 2005]

For a knot K ,

$\{J_K^{\mathfrak{g}}(\lambda)\}_{\lambda}$ is \mathfrak{q} -holonomic (except G_2)

$\{f_n(\mathfrak{q}) \in \mathbb{Z}(\mathfrak{q})\}_n$ is \mathfrak{q} -holonomic

if $\exists d \in \mathbb{N}, \exists a_\ell \in \mathbb{Z}[u, v] \ (0 \leq \ell \leq d)$

$$\text{s.t. } \sum_{\ell=0}^d a_\ell(\mathfrak{q}, \mathfrak{q}^n) f_{n+\ell}(\mathfrak{q}) = 0$$

$$(\forall n \geq 0)$$

e.g. $K = \mathcal{D}$ $(n+1)$ -dim. irrep.

$$J_K^{al_2}(n) = \frac{\mathfrak{q}^{-\frac{n-1}{2}}}{1-\mathfrak{q}^{-1}} \sum_{k=0}^{n-1} (1-\mathfrak{q}^{-n})(1-\mathfrak{q}^{1-n}) \dots (1-\mathfrak{q}^{k-n})$$

then,

$$J_K^{al_2}(n-1) = \frac{\mathfrak{q}^{n-1} + \mathfrak{q}^{4-4n} - \mathfrak{q}^{-n} - \mathfrak{q}^{1-2n}}{\mathfrak{q}^{\frac{1}{2}} (\mathfrak{q}^{n-1} - \mathfrak{q}^{2-n})} J_K^{al_2}(n)$$

$$+ \frac{\mathfrak{q}^{4-4n} - \mathfrak{q}^{3-2n}}{\mathfrak{q}^{2-n} - \mathfrak{q}^{n-1}} J_K^{al_2}(n+1)$$

• \mathcal{Q} -holonomic

$$\rightsquigarrow \delta_K(n) := \max \deg_{\mathcal{Q}} (J_K^{\text{sl}_2}(n))$$

$$\delta_K^*(n) := \min \deg_{\mathcal{Q}} (J_K^{\text{sl}_2}(n))$$

are quadratic quasi-polynomials

$$\text{i.e. } \delta_K^*(n) = a_K^*(n)n^2 + b_K^*(n)n + c_K^*(n)$$

$$\text{s.t. } a_K(n), b_K(n), c_K(n)$$

are periodic functions

for $n \gg 0$

\rightsquigarrow (strong) slope conjecture

$$\{a_K(n)\} \cup \{a_K^*(n)\}$$

$$\subset \{ \text{slopes of } \partial \Sigma \text{ s.t. } \Sigma \subset S^3 \setminus K \}$$

$$\{b_K(n)\} \cup \{b_K^*(n)\} \subset \{ \chi(\Sigma) / |\partial \Sigma| \}$$

Notation

• For $\underline{\lambda} = (\lambda_1, \lambda_2, \dots, \lambda_\ell)$

$$\underline{J}_{L, \underline{\lambda}}^{\mathcal{Q}}(\mathcal{Q}) := J_L^{\mathcal{Q}}(V_{\lambda_1}, V_{\lambda_2}, \dots, V_{\lambda_\ell})$$

• $\delta_L^*(\underline{\lambda}) := \min \deg J_{L, \underline{\lambda}}^{\mathcal{Q}}(\mathcal{Q})$

• $\hat{J}_{L, \underline{\lambda}}^{\mathcal{Q}}(\mathcal{Q}) := \pm \mathcal{Q}^{-\delta_L^*(\underline{\lambda})} J_{L, \underline{\lambda}}^{\mathcal{Q}}(\mathcal{Q}) \in \mathbb{Z}[\mathcal{Q}]$

$$= \underbrace{a_0}_{0} + a_1 \mathcal{Q} + a_2 \mathcal{Q}^2 + \dots$$

① Stability for $\{\hat{J}_{L,n}^{sl_2}(\mathfrak{g})\}_n$

conjectured by Dasbach - Lin
& proved by $\left\{ \begin{array}{l} \text{Armond} \\ \text{Garoufalidis - Lê} \end{array} \right.$

e.g. $K = \left(\begin{array}{c} \text{ } \\ \text{ } \\ \text{ } \end{array} \right)$

• table of the coefficients
of $\hat{J}_{K,n}^{sl_2}(\mathfrak{g})$ for $n=2, 3, 4$

$q^0 \ q^1 \ q^2 \ \dots$

$n=2 \quad 1 \ -1 \ -1 \ 0 \ 2 \ 0 \ -2 \ 0 \ 3 \ 0 \ -3 \ 0 \ 3 \ 0 \ -3 \ 0 \ \dots$

$n=3 \quad 1 \ -1 \ -1 \ 0 \ 0 \ 3 \ -1 \ -1 \ -1 \ -1 \ 5 \ -1 \ -2 \ -2 \ -1 \ 6 \ \dots$

$n=4 \quad 1 \ -1 \ -1 \ 0 \ 0 \ 1 \ 2 \ 0 \ -2 \ -1 \ -1 \ 1 \ 3 \ 1 \ -2 \ -3 \ \dots$

• 0-stability (the tail of K)

$n=2 \quad 1 \ -1 \ -1 \ 0 \ 2 \ 0 \ -2 \ 0 \ 3 \ 0 \ -3 \ 0 \ 3 \ 0 \ -3 \ 0 \ \dots$

$n=3 \quad 1 \ -1 \ -1 \ 0 \ 0 \ 3 \ -1 \ -1 \ -1 \ -1 \ 5 \ -1 \ -2 \ -2 \ -1 \ 6 \ \dots$

$n=4 \quad 1 \ -1 \ -1 \ 0 \ 0 \ 1 \ 2 \ 0 \ -2 \ -1 \ -1 \ 1 \ 3 \ 1 \ -2 \ -3 \ \dots$

$\downarrow \lim$

$\Phi_0 \quad 1 \ -1 \ -1 \ 0 \ 0 \ 1 \ 0 \ 1 \ 0 \ 0 \ 0 \ 0 \ -1 \ 0 \ 0 \ -1 \ \dots$

↖ tail of $\{\hat{J}_{K,n}^{sl_2}(\mathfrak{g})\}_n$

• 1-stability

$n=2 \quad 0 \ 0 \ 2 \ -1 \ -2 \ -1 \ 3 \ 0 \ -3 \ 0 \ 4 \ 0 \ -3 \ 1 \ \dots$

$n=3 \quad 0 \ 0 \ 2 \ -1 \ -2 \ -1 \ -1 \ 5 \ -1 \ -1 \ -2 \ -1 \ 7 \ \dots$

$n=4 \quad 0 \ 0 \ 2 \ -1 \ -2 \ -1 \ -1 \ 1 \ 4 \ 1 \ -2 \ -2 \ \dots$

$\Phi_1 \quad 0 \ 0 \ 2 \ -1 \ -2 \ -1 \ -1 \ 1 \ \dots$

Theorem[Armond, 2013]

L : an A -adequate link.

then, $\exists \mathcal{J}_L^{al_2}(\mathcal{Z}) \in \mathbb{Z}[[\mathcal{Z}]]$ s.t

$$\hat{\mathcal{J}}_{L,n}^{al_2}(\mathcal{Z}) - \mathcal{J}_L^{al_2}(\mathcal{Z}) \in \mathcal{O}^{n+1} \mathbb{Z}[[\mathcal{Z}]]$$

\curvearrowright tail of $\{\hat{\mathcal{J}}_{k,n}^{al_2}(\mathcal{Z})\}$

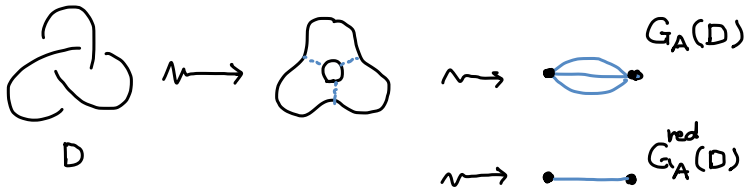
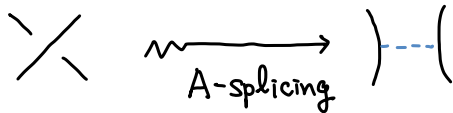
Theorem[Armond-Dasbach, 2016]

L : an A -adequate link

D : an A -adequate link diagram of L

then, $\mathcal{J}_L^{al_2}(\mathcal{Z})$ only depends on $G_A^{red}(D)$

e.g



Theorem[Garoufalidis-Lê, 2015]

L : an alternating link.

then $\{\hat{\mathcal{J}}_{L,n}^{al_2}(\mathcal{Z})\}$ is k -stable ($\forall k \geq 0$)

• $\{f_n(\mathcal{Z}) \in \mathbb{Z}[[\mathcal{Z}]]\}_n$ is k -stable

if $\exists \Phi_0(\mathcal{Z}), \dots, \Phi_k(\mathcal{Z}) \in \mathbb{Z}((\mathcal{Z}))$

$$\text{s.t. } \lim_{n \rightarrow \infty} \mathcal{O}^{k(n+1)} \left(f_n(\mathcal{Z}) - \sum_{j=0}^k \Phi_j(\mathcal{Z}) \mathcal{O}^{j(n+1)} \right) = 0$$

• $\lim_{n \rightarrow \infty} f_n(\mathcal{Z}) = \Phi(\mathcal{Z})$

$\stackrel{\text{def}}{\iff} \forall m \in \mathbb{N}, \exists N_m \in \mathbb{N}$

$$\text{s.t. } f_{N_m}(\mathcal{Z}) - \Phi(\mathcal{Z}) \in \mathcal{O}^m \mathbb{Z}[[\mathcal{Z}]]$$

Theorem[Garoufalidis-Vuong, 2017]

K : a torus knot

\mathfrak{g} : a rank 2 simple Lie algebra.

then, $\{J_{K,n,\lambda}^{\mathfrak{g}}(\mathfrak{z})\}_n$ is k -stable ($\forall k$)

$sl_3 \quad \lambda = (s, t) \quad s, t \in \mathbb{Z}_{\geq 0}$

$\{(ns, nt)\}$

$\{(n, 0)\}_n$

Theorem[Y.]

L : a "minus-adequate" oriented link.

$\exists J_L^{sl_3}(\mathfrak{z}) \in \mathbb{Z}[[\mathfrak{z}]]$ s.t.

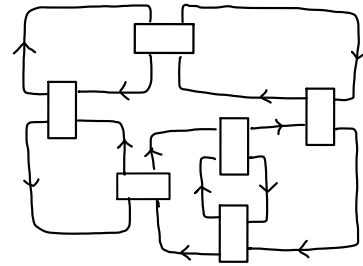
$\hat{J}_{L,(n,0)}^{sl_3}(\mathfrak{z}) - J_L^{sl_3}(\mathfrak{z}) \in \mathfrak{z}^{n+1} \mathbb{Z}[[\mathfrak{z}]]$

i.e. $\{J_{L,(n,0)}^{sl_3}(\mathfrak{z})\}$ is zero stable

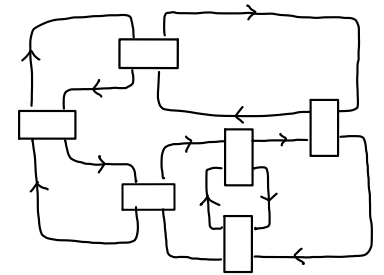
e.g. (minus-adequate)

1. Consider an adequate 4-valent graph with oriented edges

s.t. vertex =  or  or 

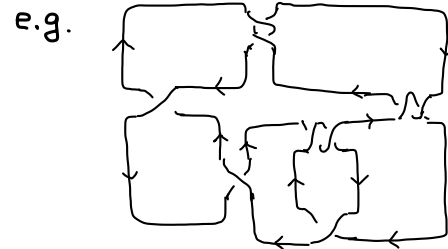
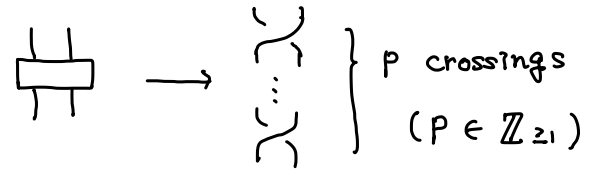


adequate



inadequate

2. Replace



§ 3 Tails and Andrews - Gordon Type Identities

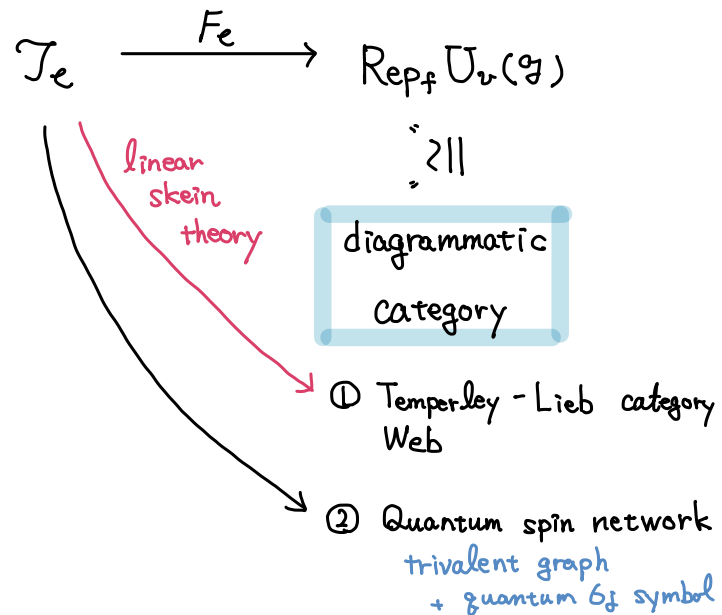
① Graphical Calculus

Problem

Compute the colored Jones polynomial and its tail.

$$\mathcal{L} = \text{Rep}_f U_q(\mathfrak{g})$$

$\mathcal{T}_\mathcal{L} = \mathcal{L}$ -colored framed tangles



"Linear skein theory"

= a functor from $\mathcal{T}_\mathcal{L}$ to a diagrammatic representation of $\text{Fun Rep}_f U_q(\mathfrak{g})$

or

$$\text{Kar}(\text{Fun Rep}_f U_q(\mathfrak{g}))$$

the Kauffman bracket ($\mathfrak{g} = \mathfrak{sl}_2$)

(Notation) $| = | 1 = \downarrow \begin{matrix} V_2 \cong V_2^* \\ \text{the 2-dim.} \\ \text{irreducible rep.} \end{matrix}$

$$| ^n = \underbrace{|| \dots ||}_n = | \begin{matrix} V_2 \otimes \dots \otimes V_2 \end{matrix}$$

the Kauffman bracket ($\mathfrak{g} = \mathfrak{sl}_2$)

$$\nearrow = q^{\frac{1}{4}} \left(\searrow + q^{-\frac{1}{2}} \cup \right)$$

$$\bigcirc = -[2] \emptyset = (q^{\frac{1}{2}} + q^{-\frac{1}{2}}) \emptyset$$

• construction of the color $|V_{n+1}$

= the Jones-Wenzl projector $\begin{array}{c} | \\ \hline | \end{array}^n$

i.e. $\begin{array}{c} | \\ \hline | \end{array}^n = \begin{array}{c} | \dots | \\ \hline | \dots | \end{array} : V_2^{\otimes n} \rightarrow \text{Sym}^n V_2 \hookrightarrow V_2^{\otimes n}$

Diagrammatic definition

$$\begin{array}{c} | \\ \hline | \end{array}^n = \begin{array}{c} | \\ \hline | \end{array}^{n-1} | + \frac{[n-1]}{[n]} \begin{array}{c} \begin{array}{c} \nearrow \\ \searrow \end{array} \\ \hline \begin{array}{c} \searrow \\ \nearrow \end{array} \end{array}^{n-1} \begin{array}{c} \nearrow \\ \searrow \end{array} \begin{array}{c} \searrow \\ \nearrow \end{array} \end{array}$$

$$\left([n] = \frac{q^{\frac{n}{2}} - q^{-\frac{n}{2}}}{q^{\frac{1}{2}} - q^{-\frac{1}{2}}} \right)$$

$$\rightsquigarrow K = \text{link}$$

then, $\begin{array}{c} | \\ \hline | \end{array}^n = J_{K,n}^{\mathfrak{sl}_2}(q) \emptyset$

the A_2 bracket ($\mathfrak{g} = \mathfrak{sl}_3$)

(Notation) $\uparrow = \uparrow_{V_{(0,0)}} = \downarrow_{V_{(0,1)}}$

$$\nearrow = q^{\frac{1}{3}} \left(\searrow - q^{-\frac{1}{6}} \begin{array}{c} \nearrow \\ \searrow \end{array} \right)$$

$$\searrow = q^{-\frac{1}{3}} \left(\nearrow - q^{\frac{1}{6}} \begin{array}{c} \searrow \\ \nearrow \end{array} \right)$$

$$\begin{array}{c} \nearrow \\ \searrow \\ \nearrow \\ \searrow \end{array} = \begin{array}{c} \searrow \\ \nearrow \end{array} + \begin{array}{c} \nearrow \\ \searrow \end{array}$$

$$\begin{array}{c} \uparrow \\ \downarrow \end{array} = [2] \uparrow, \quad \bigcirc = \begin{array}{c} \uparrow \\ \downarrow \end{array} = [3] \emptyset$$

$$\begin{array}{c} | \\ \hline | \end{array}^n = \begin{array}{c} | \\ \hline | \end{array}^{n-1} | - \frac{[n-1]}{[n]} \begin{array}{c} \begin{array}{c} \nearrow \\ \searrow \end{array} \\ \hline \begin{array}{c} \searrow \\ \nearrow \end{array} \end{array}^{n-1} \begin{array}{c} \nearrow \\ \searrow \end{array} \begin{array}{c} \searrow \\ \nearrow \end{array} \end{array}$$

$\swarrow V_{(n,0)}$

$$\begin{array}{c} m \quad n \\ \uparrow \quad \downarrow \\ \uparrow \quad \downarrow \end{array} = \sum_{k=0}^{\min\{m,n\}} (-1)^k \frac{[m][n]}{[m+n+1]} \begin{array}{c} \begin{array}{c} \nearrow \\ \searrow \end{array} \\ \hline \begin{array}{c} \searrow \\ \nearrow \end{array} \end{array}^k \begin{array}{c} \begin{array}{c} \nearrow \\ \searrow \end{array} \\ \hline \begin{array}{c} \searrow \\ \nearrow \end{array} \end{array}^{n-k} \begin{array}{c} \nearrow \\ \searrow \end{array} \begin{array}{c} \searrow \\ \nearrow \end{array} \end{array}$$

$\swarrow V_{(m,n)}$

$$\rightsquigarrow \begin{array}{c} | \\ \hline | \end{array}^n = J_{K,(m,n)}^{\mathfrak{sl}_3}(q) \emptyset$$

Twist formulas ($\mathfrak{g} = \mathfrak{sl}_2$)

Theorem[Yamada, 1989]

$$\begin{array}{c} \text{---} \\ | \\ \text{---} \end{array} \begin{array}{c} \text{---} \\ | \\ \text{---} \end{array} = \sum_{k=0}^n q^{\frac{1}{4}(-n^2+2k)} \frac{(\mathfrak{g})_n}{(\mathfrak{g})_k (\mathfrak{g})_{n-k}} \begin{array}{c} \text{---} \\ | \\ \text{---} \end{array} \begin{array}{c} \text{---} \\ | \\ \text{---} \end{array}$$

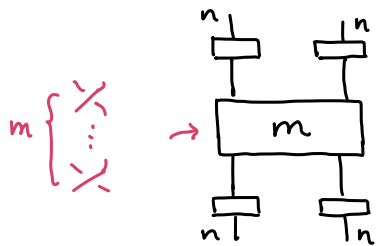
The diagram on the left shows two vertical strands, each with a box labeled 'n' at the top and bottom. The strands are connected by a crossing. The diagram on the right shows two vertical strands, each with a box labeled 'n' at the top and bottom. The strands are connected by two crossings, with a box labeled 'k' on the left and right strands, and a box labeled 'n-k' in the middle.

Theorem[Masbaum, 2003]

$$\begin{array}{c} \text{---} \\ | \\ \text{---} \end{array} \begin{array}{c} \text{---} \\ | \\ \text{---} \end{array} = \sum_{k=0}^n (-1)^{n-k} q^{\frac{1}{2}(-n^2-n+2k^2+k)} \frac{(\mathfrak{g})_n^2}{(\mathfrak{g})_k^2 (\mathfrak{g})_{n-k}} \begin{array}{c} \text{---} \\ | \\ \text{---} \end{array} \begin{array}{c} \text{---} \\ | \\ \text{---} \end{array}$$

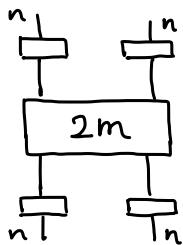
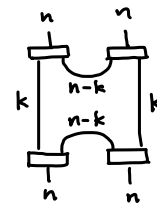
The diagram on the left shows two vertical strands, each with a box labeled 'n' at the top and bottom. The strands are connected by a crossing. The diagram on the right shows two vertical strands, each with a box labeled 'n' at the top and bottom. The strands are connected by two crossings, with a box labeled 'k' on the left and right strands, and a box labeled 'n-k' in the middle.

Theorem[Y. 2017]



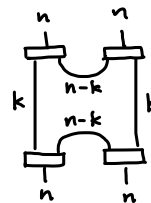
$$= (-1)^{n-k_m} q^{\frac{n-k_m}{2}} \sum_{n \geq k_1 \geq k_2 \geq \dots \geq k_m \geq 0} (-1)^{\sum_{i=1}^m k_i} q^{\frac{1}{2} \sum_{i=1}^m (k_i^2 + k_i)}$$

$$\times \frac{(q)_n}{(q)_{n-k_1} (q)_{k_1-k_2} \dots (q)_{k_{m-1}-k_m} (q)_{k_m}}$$



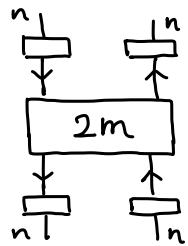
$$= q^{-\frac{m}{2}(n^2+2n)} \sum_{n \geq k_1 \geq k_2 \geq \dots \geq k_m \geq 0} (-1)^{n-k_m} q^{\frac{n-k_m}{2}} q^{\sum_{i=1}^m (k_i^2 + k_i)}$$

$$\times \frac{(q)_n^2}{(q)_{n-k_1} (q)_{k_1-k_2} \dots (q)_{k_{m-1}-k_m} (q)_{k_m}^2}$$

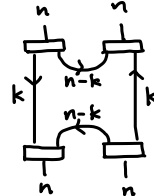


① Twist formulas for $(n,0)$ coloring of sl_3

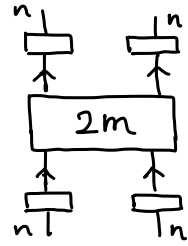
Theorem[Y. 2017] (anti-parallel case)



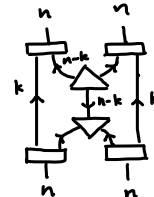
$$= q^{-\frac{2m}{3}(n^2+3n)} \sum_{n \geq k_1 \geq k_2 \geq \dots \geq k_m \geq 0} q^{n-k_m} q^{\sum_{i=1}^m (k_i^2 + 2k_i)}$$

$$\times \frac{(q)_n^2}{(q)_{n-k_1} (q)_{k_1-k_2} \dots (q)_{k_{m-1}-k_m} (q)_{k_m}^2}$$


Theorem[Y. 2020]



$$= q^{-\frac{m}{3}(n^2+3n)} \sum_{n \geq k_1 \geq k_2 \geq \dots \geq k_m \geq 0} q^{\frac{n-k_m}{2}} q^{\sum_{i=1}^m (k_i^2 + k_i)}$$

$$\times \frac{(q)_n^2}{(q)_{n-k_1} (q)_{k_1-k_2} \dots (q)_{k_{m-1}-k_m} (q)_{k_m}^2}$$


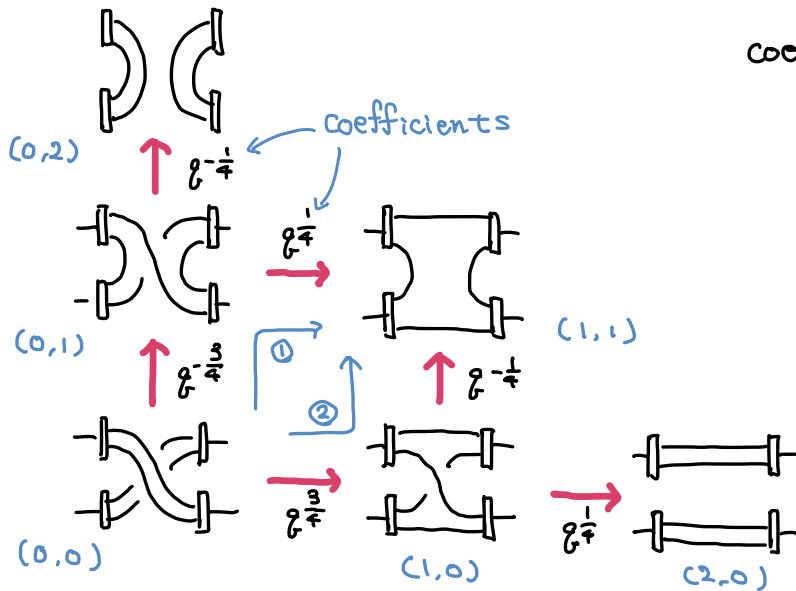
$$\left(\begin{array}{c} \text{triangle with } q \text{ on sides} \\ \downarrow \ell \end{array} = \left. \begin{array}{c} \text{stack of } \ell \text{ strands} \\ \vdots \\ \text{stack of } \ell \text{ strands} \end{array} \right\} \ell \right)$$

How to derive twist formulas (Y. 2017)

e.g.

$$\begin{aligned}
 \begin{array}{c} \text{crossing} \\ \text{with 4 strands} \end{array} &= q^{\frac{3}{4}} \begin{array}{c} \text{strand 1,2 cross} \\ \text{strand 3,4 cross} \end{array} + q^{-\frac{3}{4}} \begin{array}{c} \text{strand 1,3 cross} \\ \text{strand 2,4 cross} \end{array} \\
 &= q^{\frac{3}{4}} \left(q^{\frac{1}{4}} \begin{array}{c} \text{strand 1,2 cross} \\ \text{strand 3,4 cross} \end{array} + q^{-\frac{1}{4}} \begin{array}{c} \text{strand 1,3 cross} \\ \text{strand 2,4 cross} \end{array} \right) + q^{-\frac{3}{4}} \left(q^{\frac{1}{4}} \begin{array}{c} \text{strand 1,3 cross} \\ \text{strand 2,4 cross} \end{array} + q^{-\frac{1}{4}} \begin{array}{c} \text{strand 1,2 cross} \\ \text{strand 3,4 cross} \end{array} \right)
 \end{aligned}$$

by skein tree

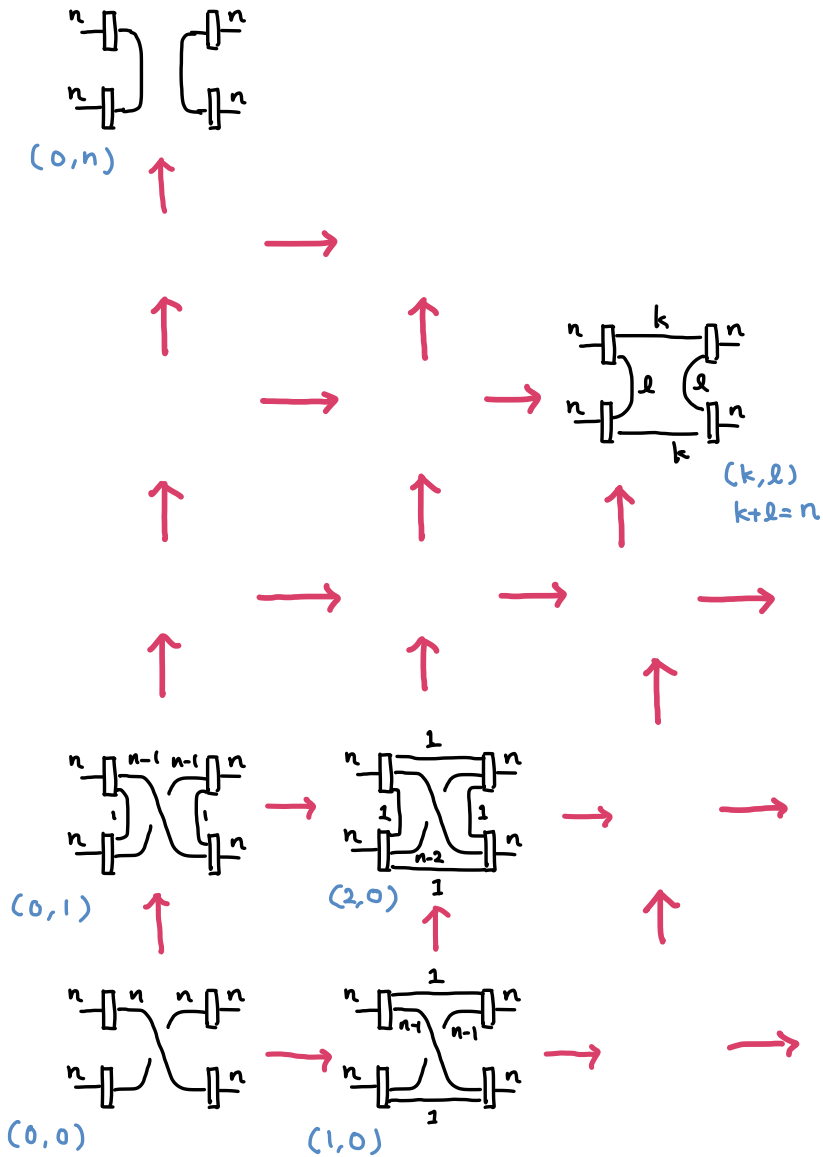


coefficient of basis web on (1,1)

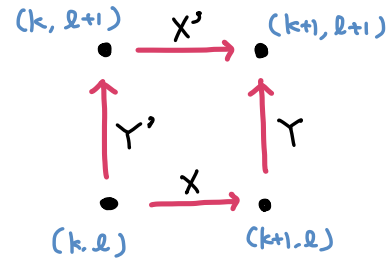
$$\begin{aligned}
 &= \sum_{\gamma: \text{paths from } (0,0) \text{ to } (1,1)} \prod w \\
 &= \frac{q^{-\frac{3}{4}} q^{\frac{1}{4}}}{\textcircled{1}} + \frac{q^{\frac{3}{4}} q^{-\frac{1}{4}}}{\textcircled{2}}
 \end{aligned}$$

$\times q$

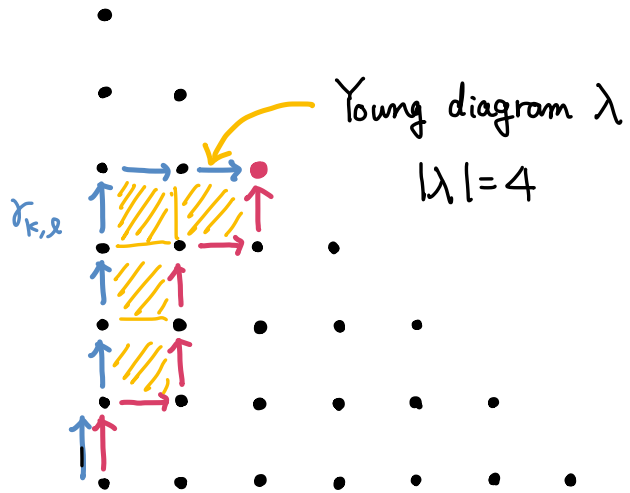
(half twist formula)



Lemma



then $XY = \varrho Y'X'$



$$\text{coeff}_r \left(\begin{array}{c} \nearrow \\ \nearrow \\ \nearrow \\ \nearrow \end{array} \right) = q^{|\lambda|} \left(\begin{array}{c} \nearrow \\ \nearrow \\ \nearrow \\ \nearrow \end{array} \right)$$

④ coefficient of (k, l) ($k+l=n$)

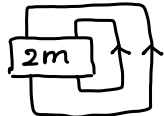
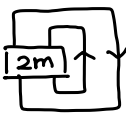
$$= \sum_{\gamma: \text{path from } (0,0) \text{ to } (k,l)} \prod_{w: \text{weight on } \gamma} w$$

$$= \left(\prod_{w: \text{weight on } \gamma_{k,l}} w \right) \left(\sum_{\substack{\lambda: \text{Young diagram} \\ \# \text{ row} \leq k \\ \# \text{ column} \leq l}} q^{|\lambda|} \right)$$

$$= \left(\prod_{w: \text{weight on } \gamma_{k,l}} w \right) \frac{(q)_n}{(q)_k (q)_{n-k}}$$

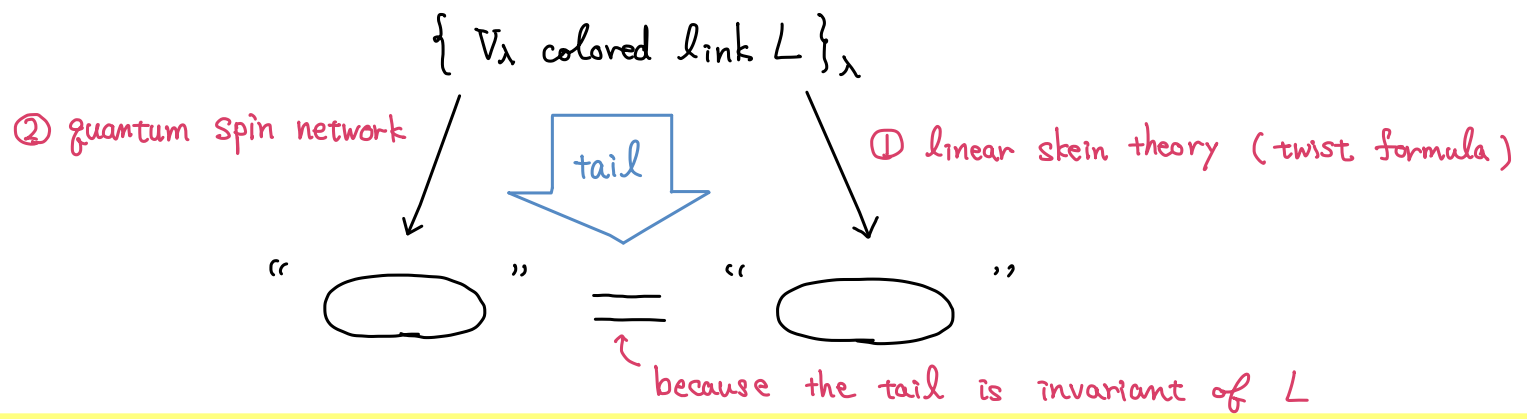
② Andrews - Gordon type identities from the tail of $T(2, m)$

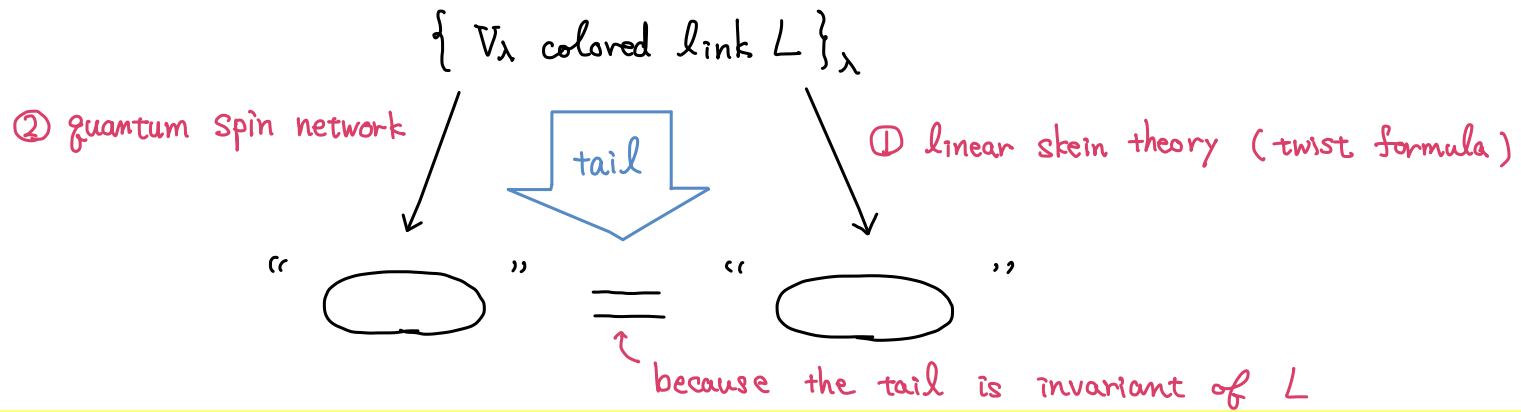
• $T(2, m) :=$  e.g. $m=2$  $m=3$ 

$T_{\frac{1}{2}}(2, 2m) :=$  $T_{\frac{1}{2}}(2, 2m) :=$ 

• $f(a, b) := \sum_{i=0}^{\infty} a^{\frac{i(i+1)}{2}} b^{\frac{i(i-1)}{2}} + \sum_{i=1}^{\infty} a^{\frac{i(i-1)}{2}} b^{\frac{i(i+1)}{2}}$: the theta series

$\psi(a, b) := \sum_{i=0}^{\infty} a^{\frac{i(i+1)}{2}} b^{\frac{i(i-1)}{2}} - \sum_{i=1}^{\infty} a^{\frac{i(i-1)}{2}} b^{\frac{i(i+1)}{2}}$: the false theta series





Theorem[Armond-Dasbach, 2011]

$$f(-q^{2m}, -q) / (1-q) = \mathcal{J}_{T(2, 2m+1)}^{sl_2}(q) = \frac{(q)_\infty}{1-q} \sum_{k_1 \geq k_2 \geq \dots \geq k_{m-1} \geq 0} \frac{q^{\sum_{i=1}^{m-1} k_i^2 + k_i}}{(q)_{k_1 - k_2} (q)_{k_2 - k_3} \dots (q)_{k_{m-2} - k_{m-1}} (q)_{k_{m-1}}}$$

Theorem[Hajij, 2015]

$$\mathcal{I}(q^{2m-1}, q) / (1-q) = \mathcal{J}_{T(2, 2m)}^{sl_2}(q) = \frac{(q)_\infty}{1-q} \sum_{k_1 \geq k_2 \geq \dots \geq k_m \geq 0} \frac{q^{-k_m} q^{\sum_{i=1}^m k_i^2 + k_i}}{(q)_{k_1 - k_2} (q)_{k_2 - k_3} \dots (q)_{k_{m-1} - k_m} (q)_{k_m}^2}$$

Theorem[Y. 2018]

$$\sum_{i=0}^{\infty} q^{-2i} q^{m(i^2+2i)} \frac{(1-q^{i+1})^3 (1+q^{i+1})}{(1-q)^2 (1-q^2)} = \mathcal{J}_{T_{\frac{1}{2}}(2,2m)}^{sl_3}(q)$$

$$= \frac{(q)_{\infty}}{(1-q)(1-q^2)} \sum_{k_1 \geq k_2 \geq \dots \geq k_m \geq 0} \frac{q^{-2k_m} q^{\sum_{i=1}^m k_i^2 + 2k_i}}{(q)_{k_1-k_2} (q)_{k_2-k_3} \dots (q)_{k_{m-1}-k_m} (q)_{k_m}^2}$$

a "diagonal summand"
of the sl_3 false theta function
in Bringmann - Kaszian - Milas

Theorem[Y. 2020]

$$\mathcal{J}_{T_{\frac{1}{2}}(2,2m+1)}^{sl_3}(q) = \frac{f(-q^{2m}, -q)}{(1-q)^2 (1-q^2)}$$

$$\mathcal{J}_{T_{\frac{1}{2}}(2,2m)}^{sl_3}(q) = \frac{\Psi(q^{2m-1}, q)}{(1-q)^2 (1-q^2)}$$

$$\rightsquigarrow \mathcal{J}_{T_{\frac{1}{2}}(2,m)}^{sl_3}(q) = \frac{1}{(1-q)(1-q^2)} \mathcal{J}_{T(2,m)}^{sl_2}(q)$$

Thank you for listening 